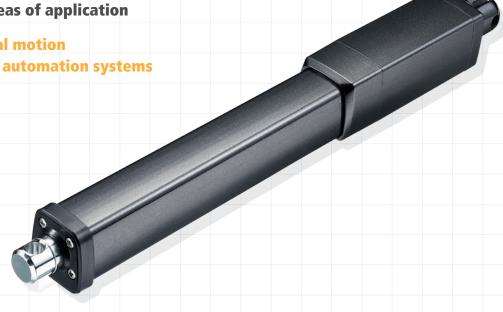
## **Typical areas of application**

- Industrial motion
- Building automation systems



The JP4 series inline linear actuator is most similar to the JP3, but was designed for industrial applications that require higher load and speed. Its IP69K protection ensures it will withstand high temperature, high pressure water jets, and the ingress of dust and other solid contaminants. For synchronization and position feedback, the JP4 can be equipped with Hall sensors.

# **Key figures**

- Voltage of motor
- Max. load
- Max. speed at full load
- Standard stroke
- Min. installation dimension
- IP rating
- Color
- Operational temperature range
- Operational temperature range at full performance
- Storage temperature range

12 V DC or 24 V DC

4500 N in push / 3000 N in pull

24.0 mm/s (with 500 N in a push or pull condition)

20 ~ 500 mm

stroke+289 mm

up to IP69K

black or grey

-5 °C ~ +65 °C

+5 °C ~ +45 °C

-40 °C ~ +70 °C

An inline actuator specially designed for small spaces.

## **Load and speed**

CODE	Lo	ad	Self locking	Typical c	urrent 2)	Typical speed			
	push	pull	force 1)	no load 24 VDC	with load 24 VDC	no load 24 VDC	full load 24 VDC		
	[N)	(N)	[N]	[A]	[A]	[mm/s)	[mm/s)		
		Motor	speed 3800 n	nin <sup>-1</sup> , duty cyc	le 10%				
В	4500	3000	4500	0.75	3.5	5.1	3.2		
С	3500	3000	3000	0.75	3.2	7.3	4.8		
D	2500	2500	2000	0.8	3.2	10.0	6.2		
E	1500	1500	1000	0.8	2.2	13.0	10.3		
F	1000	1000	700	0.8	2.2	19.0	15.5		
G	500	500	500	0.8	2.0	29.0	24.0		

#### Note

- 1) This self-locking force level is reached only when a short circuit is applied on the terminals of the motor.

  All the control boxes have this feature built-in.
- 2) With a 12 V motor, the current is approximately twice the current measured in 24 V; speed will be similar for both voltages.

## Wire definitions

CODE*	Pin 1	Pin 2	Pin 3	Pin 4	Pin 5	Pin 6
	(green)	(red)	(white)	(black)	(yellow)	(blue)
1	extend (VDC+)	N/A	N/A	N/A	retract (VDC+)	N/A
2	extend (VDC+)	N/A	middle switch pin B	middle switch pin A	retract (VDC+)	N/A
3	extend (VDC+)	common	upper limit switch	N/A	retract (VDC+)	lower limit switch
4	extend (VDC+)	common	upper limit switch	medium limit switch	retract (VDC+)	lower limit switch

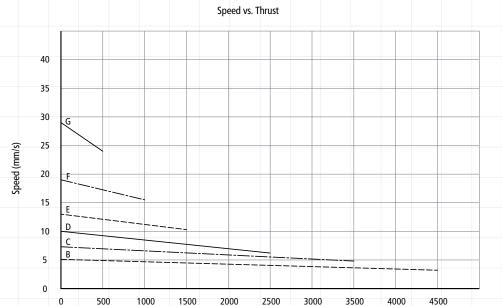
## Note

\* See ordering key – functions for limit switches.



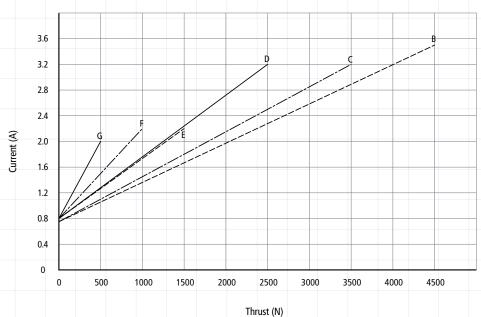
## Performance data (24 VDC motor)

Motor speed 3800 min<sup>-1</sup>, duty cycle 10%



Thrust (N)





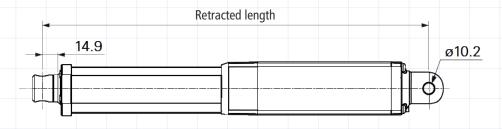
## Note

• The performance data in the curve charts shows theoretical value.

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# **Drawing**

Standard dimensions (mm)





# **Retracted length (mm)**

## Retracted length ≥ Stroke+A+B

A												
Code front atta	ichmen	it				Α						
1						+2	289					

											Щ.
В											
Stroke (mm)					В						
20~150					_						П
151~200					-						
201~250					+	10					
251~300					+	20					
301~350					+	30					
351~400					+	40					

For stroke over 400 mm + 10 mm for each incremental 50 mm stroke.



# Electric actuator JP4

Page 5

Voltage	1 = 12 V	2 = 24 V	5 = 24 V, PTC		
Load and speed	see page 2				
Stroke (mm)					
Retracted lenght (mm)	see page 5				
Rear attachment	1 = aluminum ca	sting II clevis slot 4	2 mm, depth 18.0 mm, h	nole 10.2 mm	
Front attachment		C, no slot, hole 13.0		10.2 11111	
Direction of rear atta (counterclockwise)	chment	1 = 0°			
Color	1 = black		2 = grey (Pantone	e 428C)	
IP rating	1 = without 2 = IP54	3 = IP66 5 = IP66W	6 = IP66D 7 = IP68	8 = IP69K	
Special functions for spindle sub-assembly	0 = without (standard)				
Functions for limit switches	2 = two switches 3 = two switches	at full retracted/exte at full retracted/exte	ended positions to cut cuended positions to cut cuended positions to send sended positions to sended positions	rrent + 3rd LS to send iignal	
Output signals	0 = without	1 = one Hall se	nsor 2 = two Hall sens	ors	
Connector	1 = DIN 6pin, 90	° plug	2 = tinned leads		
Cable length	0 = straight, 100 1 = straight, 500		3 = straight, 1000	) mm	

#### Terms of use

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