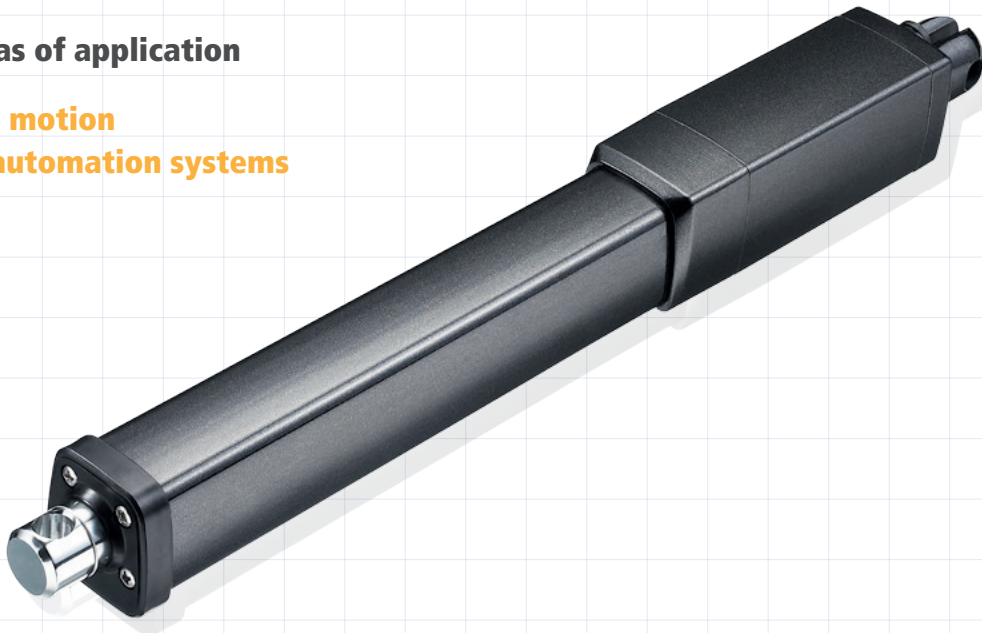


# Electric actuator JP3

## Typical areas of application

- Industrial motion
- Building automation systems



The JP3 series inline linear actuator was designed for low load industrial applications where up to IP69K dust and liquid ingress protection is necessary. It is best suited for applications with visual or compact installation dimension requirements. Hall sensors are optional for the JP3 which allow for synchronization and position feedback.

## Key figures

- |   |  |
|---|--|
| • Voltage of motor                                  | 12 V DC or 24 V DC                                 |
| • Max. load   | 2000 N in push/pull                                |
| • Max. speed at full load                           | 20.0 mm/s (with 500 N in a push or pull condition) |
| • Standard stroke                                   | 20 ~ 500 mm  |
| • Min. installation dimension                       | stroke+217 mm                                      |
| • IP rating   | up to IP69K  |
| • Color   | black or grey                                      |
| • Standards, directives                             | EN60601-1 compliant                                |
| • Operational temperature range                     | -5 °C ~ +65 °C                                     |
| • Operational temperature range at full performance | +5 °C ~ +45 °C                                     |
| • Storage temperature range                         | -40 °C ~ +70 °C                                    |

**An inline actuator specially designed for small spaces.**

## Load and speed

CODE	Load		Self locking force 1)	Typical current 2)		Typical speed	
	push [N]	pull (N)		no load 24 VDC [A]	with load 24 VDC [A]	no load 24 VDC [mm/s]	full load 24 VDC [mm/s]
<b>Motor speed 5600 min<sup>-1</sup>, duty cycle 10%</b>							
<b>B</b>	2000	2000	2000	1.0	3.0	7.5	4.2
<b>C</b>	1500	1500	1500	1.0	3.0	10.5	6.5
<b>D</b>	1000	1000	1000	1.0	3.0	15.5	9.5
<b>E</b>	500	500	500	1.0	3.0	26.5	20.0

### Note

- 1) This self-locking force level is reached only when a short circuit is applied on the terminals of the motor. All the control boxes have this feature built-in.
- 2) With a 12 V motor, the current is approximately twice the current measured in 24 V; speed will be similar for both voltages.

## Wire definitions

CODE*	Pin 1 ● (green)	Pin 2 ● (red)	Pin 3 ● (white)	Pin 4 ● (black)	Pin 5 ● (yellow)	Pin 6 ● (blue)
<b>1</b>	extend (VDC+)	N/A	N/A	N/A	retract (VDC+)	N/A
<b>2</b>	extend (VDC+)	N/A	middle switch pin B	middle switch pin A	retract (VDC+)	N/A
<b>3</b>	extend (VDC+)	common	upper limit switch	N/A	retract (VDC+)	lower limit switch
<b>4</b>	extend (VDC+)	common	upper limit switch	medium limit switch	retract (VDC+)	lower limit switch

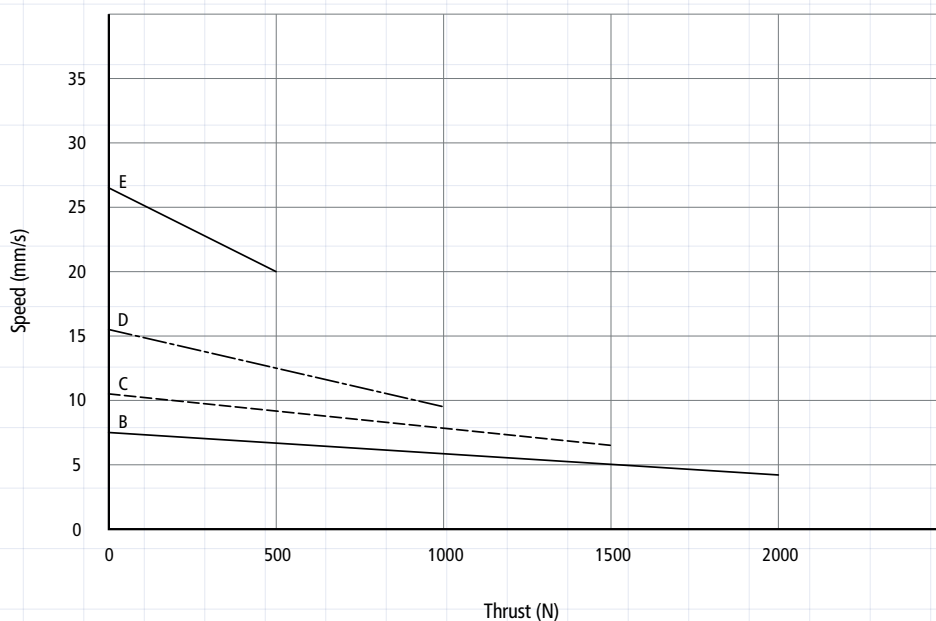
### Note

- \* See ordering key – functions for limit switches.

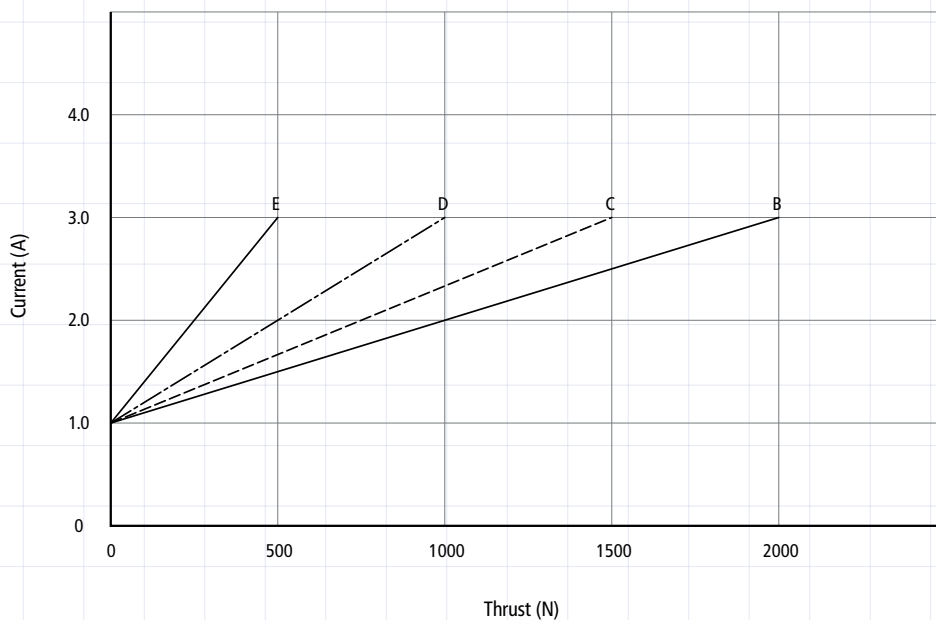
## Performance data (24 VDC motor)

Motor speed 5600 min<sup>-1</sup>, duty cycle 10%

Speed vs. Thrust



Current vs. Thrust

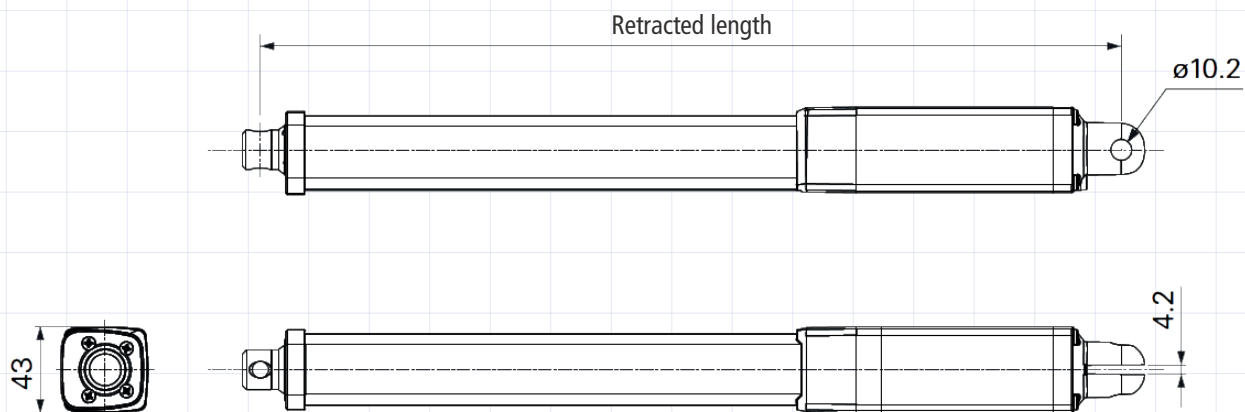


### Note

- The performance data in the curve charts shows theoretical value.

## Drawing

Standard dimensions (mm)



## Retracted length (mm)

Retracted length  $\geq$  Stroke+A+B+C

<b>A</b>	
Code front attachment	A
1	+217
2	+217
3	+230
4	+230
5	+230

<b>B</b>	
Stroke (mm)	B
20~150	-
151~200	-
201~250	+5
251~300	+10
301~350	+15
351~400	+20

<b>C</b>	
Code output signals	
0	-
1	+13
2	+13

Subject to technical changes and errors excepted.

## Ordering key (e. g.: JP3-100317-11113-01011)

JP3-

<input type="checkbox"/>	<b>Voltage</b>	1 = 12 V	2 = 24 V	5 = 24 V, PTC
<input type="checkbox"/>	<b>Load and speed</b>	see page 2		
-				
<input type="checkbox"/>	<b>Stroke (mm)</b>			
<input type="checkbox"/>				
<input type="checkbox"/>				
<input type="checkbox"/>	<b>Retracted length (mm)</b>	see page 5		
<input type="checkbox"/>				
-				
<input type="checkbox"/>	<b>Rear attachment</b>	1 = aluminum casting, U clevis, slot 4.2 mm, depth 18.0 mm, hole 10.2 mm		
<input type="checkbox"/>	<b>Front attachment</b>	1 = aluminum casting, no slot, hole 6.4 mm 2 = aluminum casting, no slot, hole 8.0 mm 3 = aluminum casting, U clevis, slot 6.0 mm, depth 13.0 mm hole 10.0 mm 4 = aluminum casting, U clevis, slot 6.0 mm, depth 13.0 mm, hole 6.4 mm 5 = aluminum casting, U clevis, slot 6.0 mm, depth 13.0 mm, hole 8.0 mm		
<input type="checkbox"/>	<b>Direction of rear attachment (counterclockwise)</b>	1 = 0°		
<input type="checkbox"/>	<b>Color</b>	1 = black	2 = grey (Pantone 428C)	
<input type="checkbox"/>	<b>IP rating</b>	1 = without 2 = IP54	3 = IP66 5 = IP66W	6 = IP66D 7 = IP68 8 = IP69K
-				
<input type="checkbox"/>	<b>Special functions for spindle sub-assembly</b>	0 = without (standard)		
<input type="checkbox"/>	<b>Functions for limit switches</b>	1 = two switches at full retracted/extended positions to cut current 2 = two switches at full retracted/extended positions to cut current + 3rd LS to send signal 3 = two switches at full retracted/extended positions to send signal 4 = two switches at full retracted/extended positions to send signal + 3rd LS to send signal		
<input type="checkbox"/>	<b>Output signals</b>	0 = without	1 = one Hall sensor	2 = two Hall sensors
<input type="checkbox"/>	<b>Connector</b>	1 = DIN 6pin, 90° plug		2 = tinned leads
<input type="checkbox"/>	<b>Cable length</b>	0 = straight, 100 mm 1 = straight, 500 mm		3 = straight, 1000 mm

## Terms of use

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